

forward:
starts with
inputs

$$z^{[0]} = b^{[0]} + w^{[0]}x = c^{[0]}$$

$$a^{[1]} = g(c^{[0]})$$

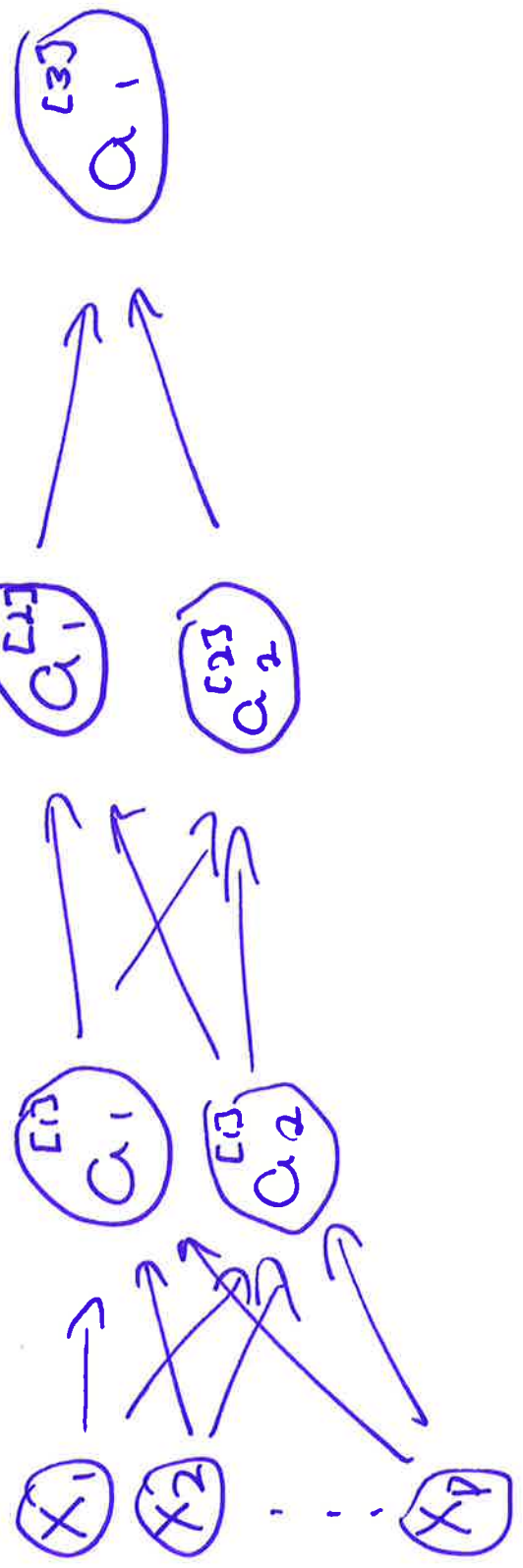
$$z^{[1]} = b^{[1]} + w^{[1]}a^{[1]} = c^{[1]}$$

$$a^{[2]} = g(c^{[1]})$$

$$z^{[2]} = b^{[2]} + w^{[2]}a^{[2]} = c^{[2]}$$

$$a^{[3]} = g(c^{[2]})$$

$$z^{[3]} = b^{[3]} + w^{[3]}a^{[3]} = c^{[3]}$$



Backward: starts
with last layer

$$\frac{\partial J}{\partial a^{[2]}} = \frac{\partial J}{\partial z^{[2]}} \cdot \frac{\partial z^{[2]}}{\partial a^{[2]}}$$

$$\frac{\partial J}{\partial z^{[2]}} = \frac{\partial J}{\partial a^{[3]}} \cdot \frac{\partial a^{[3]}}{\partial z^{[2]}}$$

$$\frac{\partial J}{\partial c^{[0]}} = \frac{\partial J}{\partial z^{[1]}} \cdot \frac{\partial z^{[1]}}{\partial c^{[0]}}$$

$$\frac{\partial J}{\partial z^{[1]}} = \frac{\partial J}{\partial a^{[1]}} \cdot \frac{\partial a^{[1]}}{\partial z^{[1]}}$$

$$\frac{\partial J}{\partial b^{[2]}} = \frac{\partial J}{\partial z^{[2]}} \cdot \frac{\partial z^{[2]}}{\partial b^{[2]}}$$

$$\frac{\partial J}{\partial w^{[2]}} = \frac{\partial J}{\partial z^{[2]}} \cdot \frac{\partial z^{[2]}}{\partial w^{[2]}}$$

$$\frac{\partial J}{\partial b^{[1]}} = \frac{\partial J}{\partial z^{[1]}} \cdot \frac{\partial z^{[1]}}{\partial b^{[1]}}$$

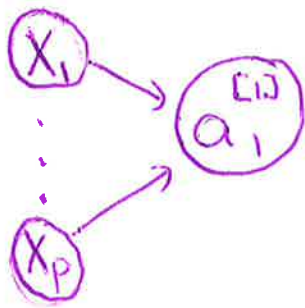
$$\frac{\partial J}{\partial w^{[1]}} = \frac{\partial J}{\partial z^{[1]}} \cdot \frac{\partial z^{[1]}}{\partial w^{[1]}}$$

These are the
numbers we
need to do
gradient descent

Previously:

①

Backpropagation for logistic regression:



$$z_1^{(i)[L]} = b^{[L]} + (w^{[L]})^T X^{(i)}$$

$$a_1^{(i)[L]} = g(z_1^{(i)[L]})$$

↑ sigmoid

$$J(b, w) = - \sum_{i=1}^m \{ y^{(i)} \cdot \log(a_1^{(i)[L]}) + (1 - y^{(i)}) \cdot \log(1 - a_1^{(i)[L]}) \}$$

We found:

$$dJdz1 = a1 - y = [a_1^{(1)[L]} - y^{(1)} \quad \dots \quad a_1^{(m)[L]} - y^{(m)}]$$

$$dJdb1 = \text{np.mean}(dJdz1, \text{axis}=1, \text{keepdims}=\text{True})$$

$$= \frac{1}{m} \sum_{i=1}^m (a_1^{(i)[L]} - y^{(i)}) \text{ as an array of shape } (1, 1) \text{ (same as b1)}$$

$$dJdw1 = (1/m) * \text{np.dot}(X, dJdz1.T)$$

↑ note: same as a0 ($a^{[0]}$)

$$\frac{\partial z_1^{(i)[L]}}{\partial w_{ip}^{[L]}} = \frac{1}{m} \begin{bmatrix} X_1^{(1)} & \dots & X_1^{(m)} \\ \vdots & & \vdots \\ X_p^{(1)} & \dots & X_p^{(m)} \end{bmatrix} \begin{bmatrix} \frac{\partial J^{(1)}}{\partial z_1^{(1)[L]}} \\ \vdots \\ \frac{\partial J^{(m)}}{\partial z_1^{(m)[L]}} \end{bmatrix}$$

← resulting shape same as w1: $(p, 1)$ ($w1^T$ shape $(1, p)$)

$$= \frac{1}{m} \begin{bmatrix} \frac{\partial J^{(1)}}{\partial z_1^{(1)[L]}} \cdot \frac{\partial z_1^{(1)[L]}}{\partial w_{ip}^{[L]}} + \dots + \frac{\partial J^{(m)}}{\partial z_1^{(m)[L]}} \cdot \frac{\partial z_1^{(m)[L]}}{\partial w_{ip}^{[L]}} \\ \vdots \\ \frac{\partial J^{(1)}}{\partial z_1^{(1)[L]}} \cdot \frac{\partial z_1^{(1)[L]}}{\partial w_{ip}^{[L]}} + \dots + \frac{\partial J^{(m)}}{\partial z_1^{(m)[L]}} \cdot \frac{\partial z_1^{(m)[L]}}{\partial w_{ip}^{[L]}} \end{bmatrix}$$

Back propagation

Main idea: One layer at a time, starting with the last layer, calculate: (suppose working on $l=2$)

- $\frac{\partial J}{\partial a_2}$: shape (n_2, m)
 - for each unit in this layer and each observation i , how does cost function change based on value of activation output for that unit and observation?
 - $np.dot(w_3, dJdz_3)$
 - ↑ $dJdz$ for next layer if not currently working on output layer
 - derivation of above formula is complicated use of chain rule.

- $\frac{\partial J}{\partial z_2}$: shape (n_2, m)
 - $dJda_2 * da_2dz_2$

element-wise product of numbers like

$$\frac{\partial J}{\partial a_j^{(i)[2]}} \cdot \frac{\partial a_j^{(i)[2]}}{\partial z_j^{(i)[2]}}$$

- $\frac{\partial J}{\partial b_2}$: shape $(n_2, 1)$
 - $np.mean(dJdz_2, axis=1, keepdims=True)$
 - $= \frac{1}{m} \sum_{i=1}^m \frac{\partial J}{\partial z_j^{(i)[2]}}$ since $\frac{\partial J}{\partial b_j} = \sum_{i=1}^m \frac{\partial J}{\partial z_j^{(i)[2]}} \cdot \frac{\partial z_j^{(i)[2]}}{\partial b_j}$

$\frac{\partial J}{\partial w_2} = (1/m) * np.dot(a_1, dJdz_2.T)$ shape (n_1, n_2)
 ↑ a_1 shape (n_1, m) after transpose, shape (m, n_2)
 same as for logistic reg, but based on a_1 instead of a_0 .

for logistic regression we did not write these two calculations down, we directly computed $\frac{\partial J}{\partial z}$

Multivariate Chain Rule from Calculus:

③

(simpler case)

Suppose $f: \mathbb{R}^k \rightarrow \mathbb{R}$ is differentiable w.r.t each of its arguments.

$$\begin{aligned} \text{Then } \frac{d}{dx} f(g_1(x), g_2(x), \dots, g_k(x)) \\ = \left\{ \frac{d}{dx} g_1(x) \right\} \cdot \frac{\partial}{\partial g_1} f(g_1, \dots, g_k) + \dots + \left\{ \frac{d}{dx} g_k(x) \right\} \frac{\partial}{\partial g_k} f(g_1, \dots, g_k) \end{aligned}$$

Example: $f(g_1, g_2) = 2g_1 + g_2$

$$g_1(x) = x^2$$

$$g_2(x) = x$$

$$\begin{aligned} f(g_1(x), g_2(x)) &= 2g_1(x) + g_2(x) \\ &= 2x^2 + x \end{aligned}$$

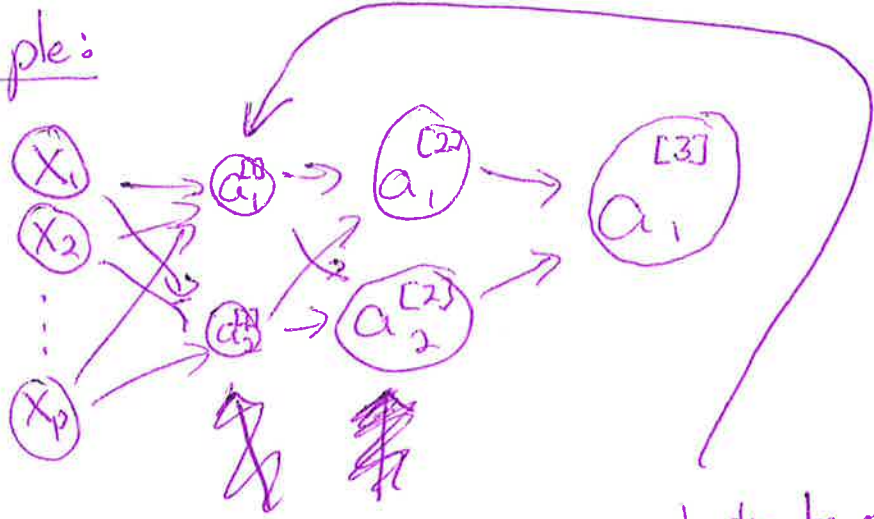
$$\frac{d}{dx} f(g_1(x), g_2(x)) = 4x + 1$$

OR

$$\begin{aligned} \frac{d}{dx} f(g_1(x), g_2(x)) &= \left\{ \frac{d}{dx} g_1(x) \right\} \cdot \frac{\partial}{\partial g_1} f(g_1, g_2) + \left\{ \frac{d}{dx} g_2(x) \right\} \cdot \frac{\partial}{\partial g_2} f(g_1, g_2) \\ &= \{2x\} \cdot 2 + \{1\} \cdot 1 \\ &= 4x + 1 \end{aligned}$$

In Backpropagation, multivariate chain rule is used to find $\frac{\partial J}{\partial a_j^{(l)[i]}}$ ← rate of change of cost function with respect to the activation value for unit j in layer $l-1$ for observation number i .

Example:



Suppose we want to know how much a change in this unit's output for observation i affects the cost function.

Need to find $\frac{\partial J}{\partial a_1^{(l)[i]}}$

How can we find this?

Note: $a_1^{(l)[i]}$ feeds into calculation of z 's for next layer:

$$z_1^{(l)[2]} = b_1^{[2]} + w_{11}^{[2]} a_1^{(l)[1]} + w_{12}^{[2]} a_2^{(l)[1]}$$

$$z_2^{(l)[2]} = b_2^{[2]} + w_{21}^{[2]} a_1^{(l)[1]} + w_{22}^{[2]} a_2^{(l)[1]}$$

so $\frac{\partial z_1^{(l)[2]}}{\partial a_1^{(l)[1]}} = w_{11}^{[2]}$ and $\frac{\partial z_2^{(l)[2]}}{\partial a_1^{(l)[1]}} = w_{21}^{[2]}$

Think of the cost function as a function of Z's from layer 1: (here, layer l=2)

$$J = J(z_1^{(1)[2]}, z_2^{(1)[2]}, \dots, z_{n_2}^{(1)[2]})$$

Each of these Z's depends on the activation output from the previous layer (in particular, on $a_2^{(1)[1]}$)

$$\text{So } \frac{\partial J}{\partial a_1^{(1)[2]}} = \frac{\partial z_1^{(1)[2]}}{\partial a_1^{(1)[2]}} \cdot \frac{\partial J}{\partial z_1^{(1)[2]}} + \frac{\partial z_2^{(1)[2]}}{\partial a_1^{(1)[2]}} \cdot \frac{\partial J}{\partial z_2^{(1)[2]}} + \dots + \frac{\partial z_{n_2}^{(1)[2]}}{\partial a_1^{(1)[2]}} \cdot \frac{\partial J}{\partial z_{n_2}^{(1)[2]}}$$

↑
weight given to $a_1^{(1)[2]}$ when calculating $z_1^{(1)[2]}$

$$= w_{11}^{[2]} \cdot \frac{\partial J}{\partial z_1^{(1)[2]}} + w_{21}^{[2]} \cdot \frac{\partial J}{\partial z_2^{(1)[2]}} + \dots + w_{n_2 1}^{[2]} \cdot \frac{\partial J}{\partial z_{n_2}^{(1)[2]}}$$

Put this together for all n_1 units in layer 1:

$$\begin{bmatrix} \frac{\partial J}{\partial a_1^{(1)[2]}} \\ \vdots \\ \frac{\partial J}{\partial a_{n_1}^{(1)[2]}} \end{bmatrix} = \begin{bmatrix} w_{11}^{[2]} \cdot \frac{\partial J}{\partial z_1^{(1)[2]}} + \dots + w_{n_2 1}^{[2]} \cdot \frac{\partial J}{\partial z_{n_2}^{(1)[2]}} \\ \vdots \\ w_{1 n_1}^{[2]} \cdot \frac{\partial J}{\partial z_1^{(1)[2]}} + \dots + w_{n_2 n_1}^{[2]} \cdot \frac{\partial J}{\partial z_{n_2}^{(1)[2]}} \end{bmatrix} = \begin{bmatrix} | & & | \\ w_{11}^{[2]} & \dots & w_{n_2 1}^{[2]} \\ | & & | \end{bmatrix} \begin{bmatrix} \frac{\partial J}{\partial z_1^{(1)[2]}} \\ \vdots \\ \frac{\partial J}{\partial z_{n_2}^{(1)[2]}} \end{bmatrix}$$

$$dJ da_1 = W \cdot dJ dz_1$$

↑
now, stack observations next to each other